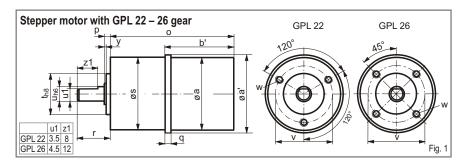
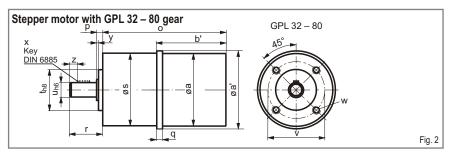
phytron

Stepper Motor with GPL Planetary Gear





	otor		Dimensions in mm															
	Stepper motor				1	1 2 3 stages												
Gear		а	a'	b'		0		р	q	r	S	t	u	٧	W	Х	у	Z
20	ZSS 19 ZSS 20	19	22	29 45.5	50 66.5	57 73.5	64 80.5	0.5	4.5	15	22	12	4	16	M2.5x4	_	0.5	_
22	ZSS 25 ZSS 26	25	25.5	33.5 49.5	54.5 70.5	61.5 77.5	68.5 84.5	2.5	5									
26	ZSS 25 ZSS 26	25	26	33.5 49.5	59 75	67 83	75 91	2.5	5	17	26	14	5	20	M3x4	-	0.5	-
32	ZSS 32 ZSS 33	32	33	40.5 59.5	69.5 88.5	78.5 97.5	87.5 106.5	4	5	20	32	20	6	26	M3x5	-	1	-
42	ZSS 41 ZSS 42 ZSS 43	42	43	53 68 83	103	100.5 115.5 130.5	128	4	7	22.5	42	25	8	32	M4x8	3x3x14	1	2.25
	ZSS 52	52	53	82.5	123.5	138	152.5								Θ	16		
52	ZSS 56 ZSS 57	56.4	57	74 90	115 131	130 145	144 160	4	9	24	52	32	12	40	M5x8	4x4x16	1	2
80	RSS 79 RSH 79	80	80	125	168.5	186.5	204.5	5	23.1	35	80	0 50	50 14	65	M6x12	κ20	2.5	5
00	RSS 80 RSH 80	80	80	147	190.5	208.5	226.5	J	20.1	33	00	30	14	03	MG	5x5x20	2.3	J

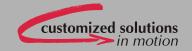
Gear	Weig	ght without in 2-stage	motor 3-stage	perm. radial load (center of shaft)	Permissible axial load	Protection class Gear	Protection class Gear + Motor		
GPL 22	50 g	75 g	100 g	30 N	24 N	IP 44	IP 40 IP 44		
GPL 26	70 g	90 g	115 g	50 N	40 N	IP 44	IP 40 IP 44		
GPL 32	135 g	180 g	250 g	80 N	65 N	IP 54	IP 40 IP 44		
GPL 42	275 g	350 g	425 g	150 N	120 N	IP 54	IP 43 IP 65		
GPL 52	475 g	600 g	725 g	250 N	200 N	IP 54	IP 43 IP 65		
GPL 80	1.5 kg	2.1 kg	2.75 kg	400 N	320 N	IP 54	IP 54 IP 65		

IP xx = Standard IP xx = optional (dimensions on request)



Technical Information

- Stepper motor mounted gear
- 200-step2-phase powerful stepper motor
- 1- to 3-stage planetary gear
- Low gear backlash
 - Standard: 20 to 50 angular minutes
 - Low-backlash: 6 to 15 angular minutes
- Maximum permanent torque 0.1 to 38 Nm
- 100% permissible short-term overload
- Adapted for permanent, alternate or intermittent operation
- Ideal for combination with toothed belt modules
- 4:1 to 256:1 reduction ratios (depending on the gear type)
- High efficiency
- Low gear inertia
- Permissible temperature range –30 to +90 °C



Mechanical Characteristics

					М	echanic	cal Gear Characteristics						
			Reduction ratios		5	standard	Ŀ	lov	v-backla	ash			
Gear	Stepper motor	Stages			No-load backlash	Nominal torque (S1)	Emergency stop torque (S1)	No-load backlash	Nominal torque (S5)	Emergency stop torque (S5)	Torsional stiffness	Average mass inertia at drive	Efficiency
						N	m		N	m	Nm/arcmin	kgcm²	%
	ZSS 19 ZSS 20 ZSS 25 ZSS 26	1	4:1 5:1	7:1	20'	0.1	0.2	-	-	-	0.19	0.008	96
GPL 22		2	16:1 20:1 28:1	35:1 49:1	35'	0.5	1	-	-	-	0.21	0.006	90
		3	64:1 80:1 112:1	140:1 196:1 245:1	50'	1.5	3	-	-	-	0.2	0.004	85
	ZSS 25 ZSS 26	1	3.5:1 4.33:1	6:1 7.67:1	20'	0.3	0.6	-	-	-	0.24	0.012	96
GPL 26		2	12.25:1 18.78:1 26:1	33.22:1 46:1	35'	1	2	-	-	-	0.26	0.010	90
		3	81.37:1 112.67:1 143.96:1	199.33:1 276:1	50'	3	6	-	-	-	0.25	0.0095	85
	ZSS 32 ZSS 33	1	4:1 4.5:1 5.2:1	6.25:1 8:1	20'	0.4	0.8	6'	0.8	1.6	0.3	0.015	96
GPL 32		2	16:1 18:1 20.8:1 25:1 29:1	32:1 36:1 41.6:1 50:1	35'	2	4	10'	4	6	0.32	0.012	90
		3	72:1 81:1 100:1 130:1	144:1 200:1 225:1 256:1	50'	6	12	15'	6	12	0.3	0.011	85
	ZSS 41 ZSS 42 ZSS 43	1	4:1 5:1	6:1	20'	0.7	1.4	6'	1.4	3	0.4	0.03	96
GPL 42		2	14:1 16:1	20:1	35'	4	8	10'	8	12	0.42	0.024	90
		3	56:1 64:1 80:1 100:1	120:1 144:1 184:1	50'	12	24	15'	12	24	0.4	0.024	85
	ZSS 52 ZSS 56 ZSS 57	1	4:1 4.5:1 5.2:1	6.25:1 8:1	20'	1.5	3	6'	3	6	1.2	0.06	96
GPL 52		2	16:1 18:1 20.8:1 25:1 29:1	32:1 36:1 41.6:1 50.1:1	35'	10	20	10'	20	30	1.3	0.055	90
		3	72:1 81:1 100:1 130:1	144:1 200:1 225:1 256:1	50'	30	60	15'	30	60	1.35	0.05	85
	RSS 79 RSH 79 RSS 80	1	4:1		20'	3	6	6'	6	12	1.5	0.12	96
GPL 80		2	14:1 16:1	20:1 24:1	35'	15	30	10'	30	38	1.5	0.08	90
	RSH 80	3	56:1	64:1	50'	38	75	15'	38	75	1.4	0.075	85

Material

Gear housing:

GPL 22: stainless steel GPL 26 – 80: rustproof for normal

environmental conditions

Output shaft bearing: 2 deep groove ball bearings

Grease Lubrication

Maintenance-free permanent lubrication with grease of the highest quality.

After three years or every 10,000 hours of operation we recommend servicing.

Operating Modes

S1: Continuous operation

The gear box's operating time exceeds 15 minutes without a break or the duty cycle is more than 60%. In no case the gear box housing temperature may exceed 70 °C.

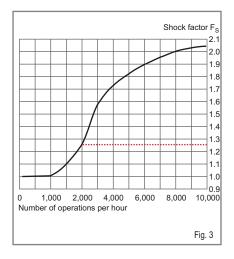
S5: Cyclical operation

The gear box's duty cycle is less than 60%. The number of operations per hour can range anywhere from a few to several thousand.

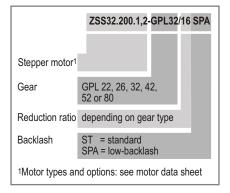
If the number of operations exceeds 1000 per hour, the maximum torque occuring has to be multiplied by a shock factor (fig. 3) to take into account the additional dynamic load.

The data in this publication are based on software models and empirical values for the S1 and S5 modes and on a shock factor of 1.25.

Shock Factor



Ordering Data





in motion

